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payload or other attachments) will run for up to 3.5 hours with a fully charged APS battery. • When you charge an iRobot rechargeable battery for the first time, or if iRobot Create has been left on and not charging, the robot initiates a special 16-hour reconditioning charge cycle. Page 18:

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iRobot - Owner Manual Roomba I
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(Vpwr) are connected to the Roomba battery through a 200 mA PTC resettable fuse. The continuous draw from these two pins together should not exceed 200 mA. Do not draw more than 500 mA peak from these pins, or the fuse will reset.

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integrate them into an SoC (system on a chip) framework, realize the system on an FPGA prototyping board, and verify the hardware and software operation. The examples start with simple gate-level circuits, progress gradually through the RT (register transfer) level modules, and lead to a

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width modulation) controller, I2C controller, SPI controller, and XADC (Xilinx analog-to-digital converter) controller. Introduces a music synthesizer constructed with a DDFS (direct digital frequency synthesis) module and an ADSR (attack-decay-sustain-release) envelope generator.

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Expands the original video controller into a complete stream based video subsystem that incorporates a video synchronization circuit, a test-pattern generator, an OSD (on-screen display) controller, a sprite generator, and a frame buffer. Provides a detailed discussion on blocking and

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nonblocking statements and coding styles. Describes basic concepts of software-hardware co-design with Xilinx MicroBlaze MCS soft-core processor. Provides an overview of bus interconnect and interface circuit. Presents basic embedded system software development. Suggests

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and Phone utilities. New to this edition are additional insights into application development and sending e-mail to remote notes via the Internet, remote logins and file transfers. Each chapter is liberally sprinkled with learning aids including summaries and tables of commands, exercises, and review

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quizzes. Completely covers the OpenVMS operating system - from logging in to creating command procedures, with thorough discussions of files and directories Covers both EVE and EDT editors in detail Shows how to customize your working environment

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In recent years, robots have been built based on cognitive architecture which has been developed to model human cognitive ability. The cognitive architecture can be a basis for intelligence technology to generate robot intelligence. In this edited book

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the robot intelligence is classified into six categories: cognitive intelligence, social intelligence, behavioral intelligence, ambient intelligence, collective intelligence and genetic intelligence. This classification categorizes the intelligence of robots based on the different aspects of

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awareness and the ability to act deliberately as a result of such awareness. This book aims at serving researchers and practitioners with a timely dissemination of the recent progress on robot intelligence technology and its applications, based on a collection of papers presented at

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the 1st International Conference on Robot Intelligence Technology and Applications (RiTA), held in Gwangju, Korea, December 16-18, 2012. For a better readability, this edition has the total 101 papers grouped into 3 chapters: Chapter I: Cognitive Intelligence, Social Intelligence and

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Behavioral Intelligence, Chapter II:
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Chapter III: Intelligent Robot
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Conference on Futuristic Trends in Network and Communication Technologies, FTNCT 2018, held in Solan, India, in February 2018. The 37 revised full papers presented were carefully reviewed and selected from 239 submissions. The prime aim of the conference is to invite researchers

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from different domains of network and communication technologies to a single platform to showcase their research ideas. The selected papers are organized in topical sections on communication technologies, Internet of Things (IoT), network technologies, and wireless networks.

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This book constitutes the refereed proceedings of the 24th Australasian Joint Conference on Artificial Intelligence, AI 2011, held in Perth, Australia, in December 2011. The 82 revised full papers presented were carefully reviewed and selected from

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193 submissions. The papers are organized in topical sections on data mining and knowledge discovery, machine learning, evolutionary computation and optimization, intelligent agent systems, logic and reasoning, vision and graphics, image processing, natural language

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number of users, provide support for different services, guarantee the QoS, and optimize the network resources. For these networks, there are many research issues and challenges that should be considered and find solutions. .

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